

# SOLUTIONS - FIRST HOUR TEST - EEL 3473 - Sept 25, 2009

1. Discuss the concept of a "skin depth" in no more than one page.

In any material with constant conductivity  $\sigma$  and permittivity  $\epsilon$ , the phasor (one frequency) plane wave electric field is

$$\vec{E} = E_0^+ e^{-\alpha z} e^{-j\beta z} \quad \text{in the } +z \text{ direction}$$

We define the skin depth  $\delta_s = \frac{1}{\alpha}$ , so

$$\vec{E}(z) = E_0^+ e^{-z/\delta_s} e^{-j\beta z}$$

Thus, when the wave has propagated  $z = \delta_s$  the amplitude is decreased  $e^{-1} = \frac{1}{e} \approx 1/3$

For a general material with  $\sigma, \epsilon$

$$\alpha = \frac{1}{\delta_s} = \omega \left( \frac{\mu\epsilon}{2} \left[ \sqrt{1 + \left(\frac{\epsilon''}{\epsilon}\right)^2} - 1 \right] \right)^{1/2}$$

$$\text{with } \epsilon'' = \sigma/\omega$$

For a good conductor, the most common situation in which a skin depth  $\delta_s$  is used,

$$\frac{\epsilon''}{\epsilon} = \frac{\sigma}{\omega\epsilon} \gg 1$$

$$\text{and hence } \alpha = \frac{1}{\delta_s} = \sqrt{\pi f \mu \sigma}$$

where  $\mu$  is the permeability

The skin depth for a good conductor is inversely proportional to the square root of frequency and of conductivity,  $\delta_s = \frac{1}{\sqrt{\pi f \mu \sigma}}$

In a good conductor the  $\vec{J} \cdot \vec{E}$  ( $I^2 R$ ) heating losses cause the Poynting vector  $\vec{S}$  to decrease  $\sim (e^{-z/\delta_s})^2$  with  $z$

2. Discuss the relationship between value of the relaxation time,  $\tau = \epsilon/\sigma$ , for charge dispersal in a material and the characteristics of the plane waves that can propagate in that material. Use less than one page.

In a material with constant  $\sigma$  and constant  $\epsilon$ , any <sup>group of</sup> charges will disperse with time as  $e^{-z/\tau}$  with  $\tau = \epsilon/\sigma$ . The dispersion (or decrease) is driven by the electric field of the charges themselves.

When a propagating electromagnetic wave traverses the material, its electric field will also drive charge motion. If the period of the wave  $T$  ( $T = 1/f$ ) is small compared to  $\tau$ , there is no time for any charge to interact with itself during many periods of the wave and the material appears to the wave to be an insulator  $T = \frac{1}{f} \ll \tau = \epsilon/\sigma$  or  $\sigma \ll \omega \epsilon$  where  $\omega = 2\pi f$

For the wave  $\vec{\nabla} \times \vec{H} = \underbrace{\sigma \vec{E}}_{\text{cond. current}} + \underbrace{j\omega \epsilon \vec{E}}_{\text{displacement current}}$

so, if  $\sigma \ll \omega \epsilon$   $\vec{\nabla} \times \vec{H} \approx j\omega \epsilon \vec{E}$ , and the wave phase vel =  $\frac{1}{\sqrt{\mu \epsilon}}$

Conversely, if  $T \gg \tau$ , the charge in the material has time to react before the wave amplitude changes and  $\sigma \gg \omega \epsilon$ ,  $\vec{\nabla} \times \vec{H} = \sigma \vec{E}$ , and the Maxwell eqns sol. for  $\vec{E}$  is

$$\vec{E} = E_0^+ e^{-z/\delta_s} e^{-jz/\delta_s}, \quad \delta_s = \frac{1}{\sqrt{\pi \mu \sigma \omega}}$$

$$\vec{E}(z,t) = E_0^+ e^{-z/\delta_s} \cos(\omega t - z/\delta_s) \quad \text{with } \delta_s \ll \frac{1}{\sqrt{\mu \epsilon}}$$

3. Define the Poynting vector and sketch (or discuss) how it is derived. Use less than one page.

In the time domain

$$\vec{S}(\vec{r}, t) = \vec{E} \times \vec{H} \quad \text{watts/m}^2, \quad \vec{E}(\vec{r}, t), \vec{H}(\vec{r}, t)$$

In the phasor domain

$$\vec{S}(\vec{r}) = \vec{E} \times \vec{H}^*, \quad \vec{S}(\vec{r}, t) = \frac{1}{2} \text{Re}(\vec{E} \times \vec{H}^*)$$

for one frequency

$\vec{S}$  is the energy in the wave passing per unit area in unit time

$-\oint \vec{E} \times \vec{H} \cdot d\vec{s}$  is the total energy through the closed surface ~~of~~ any volume surrounding

It can be shown from Maxwell's curl equations

Heat

diff. area  $d\vec{S}$

Vol.

Poynting vector  $\vec{S}$

power into volume

surf. area

$$-\oint \vec{E} \times \vec{H} \cdot d\vec{s} = \underbrace{\iiint \vec{E} \cdot \frac{d\vec{D}}{dt} dV}_{\text{increase with time of electric energy storage}} + \underbrace{\iiint \vec{H} \cdot \frac{\partial \vec{B}}{\partial t} dV}_{\text{increase in time of magnetic energy storage}} + \underbrace{\iiint \vec{E} \cdot \vec{J} dV}_{\text{power to heat (I}^2\text{R) is volume}}$$

Sketch of Proof

$$\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

dot  $\vec{E}$  into both sides

$$\vec{E} \cdot \nabla \times \vec{H} = \vec{E} \cdot \vec{J} + \vec{E} \cdot \frac{\partial \vec{D}}{\partial t}$$

use vector identities and  $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

to get above eqn with left hand =  $-\iiint \nabla \cdot (\vec{E} \times \vec{H}) dV$   
 which, from divergence theorem, yields the above

4. Write a mathematical expression in both the time-domain and frequency domain for (1) a linearly polarized plane wave and (2), a circularly polarized one.

wave in  
+z dir.

General:

$$\vec{E} = (a_x \hat{x} + a_y e^{j\delta} \hat{y}) e^{-jkz} \quad (\text{phasor plane wave})$$

$$\vec{E}(z, t) = a_x \cos(\omega t - kz) \hat{x} + a_y \cos(\omega t - kz + \delta) \hat{y}$$

(time domain)

for linear polarization,  $\delta = 0, \pi$   
 $a_x, a_y$  arbitrary

for circular polarization  $\delta = \pm \pi/2$   
 $a_x = a_y = a$

(1) linearly polarized

$\vec{E}(z) = a_x e^{-jkz} \hat{x}$	← freq. domain
$\vec{E}(z, t) = a_x \cos(\omega t - kz) \hat{x}$	← time domain

one of many (basically 3) possibilities

(2) left circularly polarized

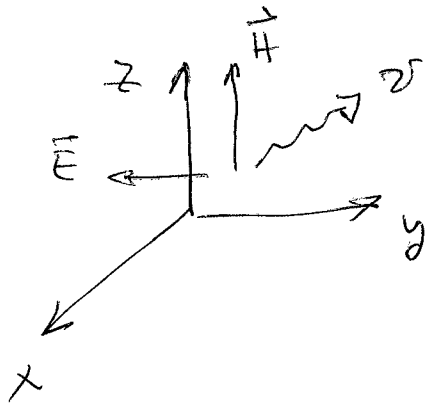
$\vec{E}(z) = (a \hat{x} + a e^{j\pi/2} \hat{y}) e^{-jkz}$	← freq. domain
$\vec{E}(z, t) = a \cos(\omega t - kz) \hat{x} - a \sin(\omega t - kz) \hat{y}$	← time domain

one of two possibilities

or equivalently

$$-a \cos(\omega t - kz + \frac{\pi}{2}) \hat{y}$$

5. A uniform plane wave has a magnetic field intensity  $\vec{H} = \hat{z} A \sin(dt + bx)$ . (1) In what direction is the wave propagating and (2) in what direction is the accompanying electric field?



dir. of prop =  $\vec{E} \times \vec{H}$ ,  
 so  
 $\vec{E}$  in  $-\hat{y}$

$\sin(dt + bx)$   
 means  
 going in  
 $-\hat{x}$  direction  
 because to keep  
 phase constant,  
 $x$  must get smaller  
 as time increases

① direction =  $-\hat{x}$

②  $\vec{E} = -\hat{y}$